

init.cpp

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```
#include "airbot_sdk.hpp"
using namespace airbot;
int main() {
    auto sdk = std::make_shared<AirbotSdk>("192.168.0.xxx", 50051);
    if (sdk->IsRunning()) {
        sdk->GetLogger()->info("SDK start running:");
        sdk->GetLogger()->info("Product Info:");
        auto info = sdk->GetProductInfo();
        for (const auto& [key, value] : info) {
            std::string value_str;
            for (const auto& val : value) {
                value_str += val + " ";
            }
            if (!value_str.empty()) {
                value_str.pop_back();
            }
            sdk->GetLogger()->info("{}: {}", key, value_str);
        }
    }
    return 0;
}
```